

Warm up spin 1/2 Hubbard U, V model

$$H = -t \sum_{\langle ij \rangle} c_{i\sigma}^\dagger c_{j\sigma} + U \sum_{\langle i \rangle} n_{i\uparrow} n_{i\downarrow} + V \sum_{\langle i, i+1 \rangle} n_i n_{i+1}$$

useful identity : define $N^\dagger = \psi_{R\sigma}^\dagger \psi_{L\sigma}$, $\vec{N}^\dagger = \psi_{R\alpha}^\dagger (\frac{\sigma}{2})_{\alpha\beta} \psi_{L\beta}$

$$N^\dagger N = -\frac{1}{2} J_R \cdot J_L - 2 \vec{J}_R \cdot \vec{J}_L, \quad \vec{N}^\dagger N = -\frac{3}{8} J_R J_L + \frac{1}{2} \vec{J}_R \cdot \vec{J}_L$$

$$\therefore n_{i\uparrow} n_{i\downarrow} = \frac{1}{2} (n_{i\uparrow} + n_{i\downarrow})^2 - n_{i\uparrow} - n_{i\downarrow} = \frac{1}{2} [J_R + J_L + N^\dagger e^{-2ik_F x} + N e^{2ik_F x}]^2$$

$$\begin{aligned} \rightarrow J_R \cdot J_L + N^\dagger N &= \frac{1}{2} J_R J_L - 2 \vec{J}_R \cdot \vec{J}_L, \quad \text{where } J_{R,L} = \psi_{R\sigma}^\dagger \psi_{L\sigma} \\ &+ \frac{1}{2} (N^\dagger N e^{-4ik_F x} + \text{h.c.}) \quad + e^{-i4k_F x} (\psi_{R\uparrow}^\dagger \psi_{R\downarrow}^\dagger \psi_{L\downarrow} \psi_{L\uparrow}) + \text{h.c.} \\ &\quad \psi_{R,\alpha}^\dagger (\frac{\sigma}{2})_{\alpha\beta} \psi_{L\beta} \end{aligned}$$

$$n(x)n(x+a) = [J_L(x) + J_R(x) + e^{-i2k_F x} N(x) + e^{i2k_F x} N(x)] [J_L(x) + J_R(x) + e^{-2ik_F a} e^{-i2k_F x} N(x) + e^{2ik_F a} e^{i2k_F x} N(x)]$$

$$\sim 2J_L(x)J_R(x) + (e^{2ik_F a} + e^{-2ik_F a}) N(x)N(x) + \{e^{-i4k_F x} e^{-2ik_F a} N(x)N(x) + \text{h.c.}\}$$

$$= 2J_L(x)J_R(x) + 2\cos 2k_F a [-\frac{J_R J_L}{2} - 2\vec{J}_R \cdot \vec{J}_L] + 2[e^{-i4k_F x} e^{-2ik_F a} \psi_{R\uparrow}^\dagger \psi_{R\downarrow}^\dagger \psi_{L\downarrow} \psi_{L\uparrow} + \text{h.c.}]$$

So only including non-chiral interaction:

$$H_0 = \frac{\pi v_F}{2} \int dx (J_L^2 + J_R^2) + \frac{2\pi}{3} v_F \int dx [\vec{J}_R^2 + \vec{J}_L^2]$$

$$\text{Hint} = [\frac{U}{2} + (2 - \cos 2k_F a) V] J_L J_R + (-2U - 4V \cos 2k_F a) \vec{J}_R \cdot \vec{J}_L$$

$$\{ [u + 2ve^{-2ik_F a}] \psi_{R\uparrow}^\dagger \psi_{R\downarrow}^\dagger \psi_{L\downarrow} \psi_{L\uparrow} + \text{h.c.} \}$$

$$J_L = \sqrt{\frac{2}{\pi}} \partial_x \phi_{c,L}, \quad J_R = \sqrt{\frac{2}{\pi}} \partial_x \phi_{c,R}$$

$$J_L^2 + J_R^2 = \frac{2}{\pi} \{ [\partial_x \phi_{c,L}]^2 + (\partial_x \phi_{c,R})^2 \} = \frac{1}{\pi} [(\partial_x \phi_c)^2 + (\partial_x \theta_c)^2]$$

$$J_L \cdot J_R = \frac{2}{\pi} [\partial_x \phi_{c,L} \cdot \partial_x \phi_{c,R}] = \frac{1}{2\pi} [(\partial_x \phi_c)^2 - (\partial_x \theta_c)^2]$$

$$\rightarrow H_c = \frac{1}{2} (v_F) [(\partial_x \phi_c)^2 + (\partial_x \theta_c)^2] + \frac{1}{2\pi} \left[\frac{u}{2} + (2 - \cos 2k_F) V \right] [(\partial_x \phi_c)^2 - (\partial_x \theta_c)^2]$$

$$- \frac{(u-2V)}{2(\pi a)^2} \cos(\sqrt{8\pi} \phi_c - (4k_F - G)x)$$

$$\psi_{R\uparrow}^+ \psi_{R\downarrow}^+ \psi_{L\downarrow} \psi_{L\uparrow} = \frac{1}{(2\pi a)^2} e^{-i\sqrt{4\pi} \phi_{R\uparrow}} e^{-i\sqrt{4\pi} \phi_{L\uparrow}} e^{-i\sqrt{4\pi} \phi_{R\downarrow}} e^{-i\sqrt{4\pi} \phi_{L\downarrow}}$$

$$= \frac{1}{(2\pi a)^2} e^{-i\sqrt{4\pi} \phi_{\uparrow}} e^{-\frac{4\pi}{2} [\phi_{R\uparrow} \phi_{L\uparrow}]} e^{-i\sqrt{4\pi} \phi_{\downarrow}} e^{-\frac{4\pi}{2} [\phi_{R\downarrow} \phi_{L\downarrow}]}$$

$$[\phi_{R\uparrow} \phi_{L\uparrow}] = \frac{1}{4}$$

$$= \frac{-1}{(2\pi a)^2} e^{-i\sqrt{8\pi} \phi_c}$$

$$\text{i.e. } H_c = \underbrace{\left[\frac{1}{K_c} (\partial_x \phi_c)^2 + K_c (\partial_x \theta_c)^2 \right]}_{\frac{v_c}{2}} - \frac{g_c}{2(\pi a)^2} \cos(\sqrt{8\pi} \phi_c - (4k_F - G)x)$$

$$\text{where } v_c = \sqrt{v_F^2 - \left[\frac{1}{\pi} \left(\frac{u}{2} + 3V \right) \right]^2}, \quad K_c = \sqrt{\frac{v_F - \frac{1}{\pi} \left[\frac{u}{2} + 3V \right]}{v_F + \frac{1}{\pi} \left[\frac{u}{2} + 3V \right]}}$$

$$g_c = (u - 2V)$$

$$J_R^z = \sqrt{\frac{1}{2\pi}} \partial_x \phi_{SR}$$

$$J_L^z = \sqrt{\frac{1}{2\pi}} \partial_x \phi_{SL}$$

$$H_S = \frac{1}{2} (v_F) \left[(\partial_x \phi_S)^2 + (\partial_x \theta_S)^2 \right] - (2u - 4V) \frac{1}{8\pi} \left[(\partial_x \phi_S)^2 - (\partial_x \theta_S)^2 \right]$$

$$+ \frac{(u - 2V)}{2(\pi a)^2} \cos \sqrt{8\pi} \phi_S$$

$$\frac{J_R^+ J_L^- + J_R^- J_L^+}{2} = \frac{1}{2} \left[\psi_{R\uparrow}^+ \psi_{L\downarrow}^+ \psi_{R\downarrow}^- \psi_{L\uparrow}^- + \text{h.c.} \right] = \frac{1}{2} \frac{1}{(2\pi a)^2} \left[e^{-i\sqrt{4\pi} \phi_{R\uparrow}} e^{-i\sqrt{4\pi} \phi_{L\downarrow}} e^{i\sqrt{4\pi} \phi_{L\downarrow}} e^{i\sqrt{4\pi} \phi_{R\uparrow}} + \text{h.c.} \right]$$

$$= \frac{1}{2} \frac{1}{(2\pi a)^2} \left[e^{-i\sqrt{4\pi} \phi_S} e^{-\frac{4\pi}{2} \frac{i}{4}} e^{i\sqrt{4\pi} \phi_S} e^{-\frac{4\pi}{2} \frac{-i}{4}} + \text{h.c.} \right] = \frac{1}{(2\pi a)^2} \cos \sqrt{8\pi} \phi_S$$

$$H_S = \frac{v_S}{2} \left[\frac{1}{K_S} (\partial_x \phi_S)^2 + K_S (\partial_x \theta_S)^2 \right] + \frac{g_S}{2(\pi a)^2} \cos \sqrt{8\pi} \phi_S$$

$$v_S = \sqrt{(v_F)^2 - \left(\frac{u - 2V}{2\pi} \right)^2}$$

$$K_S = \sqrt{\frac{v_F + \frac{u - 2V}{2\pi}}{v_F - \frac{u - 2V}{2\pi}}}$$

$$g_S = u - 2V$$

g_c	g_s	$\langle \phi_c \rangle$	ϕ_s	
$+\infty$	0	0	/	Mott phase
	$-\infty$	0	0	\mathcal{O}_{BW}
0	0	/	/	Luttinger liquid
	$-\infty$	/	0	Luther - Emery spin gap phase
$-\infty$	0	$\sqrt{\frac{\pi}{8}}$	/	Mott phase
	$-\infty$	$\sqrt{\frac{\pi}{8}}$	0	\mathcal{O}_{CDW}

order operator :

$$\mathcal{O}_{\text{COW}} = \frac{2}{\pi a} \sin(\sqrt{2\pi} \phi_c - \delta\pi x) \cos\sqrt{2\pi} \phi_s$$

$$\mathcal{O}_{\text{BW}} = \frac{2}{\pi a} \cos(\sqrt{2\pi} \phi_c - \delta\pi x - \frac{\pi}{2} \delta) \cos\sqrt{2\pi} \phi_s$$

$$\mathcal{O}_{\text{SDW}} \begin{pmatrix} z \\ x \\ y \end{pmatrix} = \frac{1}{\pi a} \cos(\sqrt{2\pi} \phi_c + \delta\pi x) \begin{pmatrix} \sin\sqrt{2\pi} \phi_s \\ -i\eta_{\uparrow}\eta_{\downarrow} \sin\sqrt{2\pi} \theta_s \\ -i\eta_{\uparrow}\eta_{\downarrow} \cos\sqrt{2\pi} \theta_s \end{pmatrix}$$

$$\Delta = \frac{\eta_{\uparrow}\eta_{\downarrow}}{\pi a} \frac{1}{\sqrt{2}} e^{i\sqrt{2\pi} \theta_c} \cos\sqrt{2\pi} \phi_s$$

$$\Delta_{10} = \frac{i\eta_{\uparrow}\eta_{\downarrow}}{\pi a} \frac{1}{\sqrt{2}} e^{i\sqrt{2\pi} \theta_c} \sin\sqrt{2\pi} \phi_s$$

$$y = \frac{1}{\pi a} \frac{1}{\sqrt{2}} e^{i\sqrt{2\pi} \theta_c} \cos\sqrt{2\pi} \theta_s$$

$$x = \frac{1}{\pi a} \frac{1}{\sqrt{2}} e^{i\sqrt{2\pi} \theta_c} \sin\sqrt{2\pi} \theta_s$$

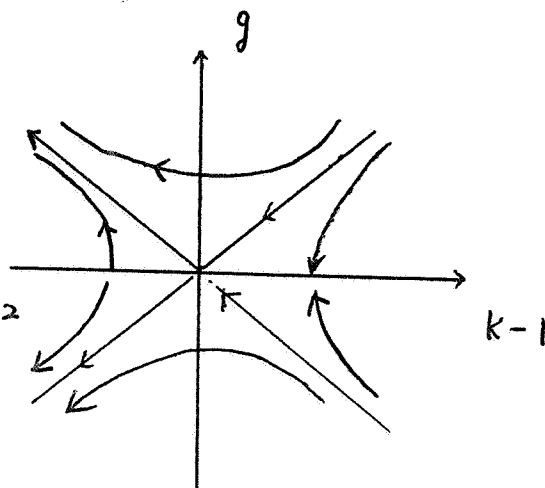
RG

$$\begin{cases} \frac{dg}{d \ln \lambda} = (2 - 2K)g \\ \frac{dK}{d \ln \lambda} = -\frac{K^2}{2\pi^2} g^2 \end{cases}$$

Correct to second order

$$\frac{d(K-1)^2}{d \ln \lambda} = -\frac{g^2}{\pi^2} (K-1) = \frac{1}{2\pi^2} g dg = d\left(\frac{g}{2\pi}\right)^2$$

$$\Rightarrow \text{separatrix} \quad K-1 = \pm \frac{g}{2\pi}$$



We can also use some simple method:

for spin 1/2 case

Let's use spin 1/2 system as an example - $\psi_{R\alpha}^+ \psi_{R\beta} \psi_{L\beta}^+ \psi_{L\alpha} = N^\dagger N$

$$N^\dagger N = a \psi_{R\alpha}^+ \psi_{R\alpha} \psi_{L\beta}^+ \psi_{L\beta} + \frac{b}{4} (\psi_{R\alpha}^+ \vec{\sigma}_{\alpha\beta} \psi_{R\beta}) (\psi_{L\beta}^+ \vec{\sigma}_{\beta\delta} \psi_{L\delta})$$

Choose $\alpha = \beta = \uparrow \Rightarrow -1 = a + \frac{b}{4}$

left hand side - $\psi_{R\uparrow}^+ \psi_{L\uparrow} \psi_{L\uparrow}^+ \psi_{R\uparrow}$

choose $\alpha = \uparrow, \beta = \downarrow$, LHS: $-\psi_{R\uparrow}^+ \psi_{R\downarrow} \psi_{L\downarrow}^+ \psi_{L\uparrow} \Rightarrow -1 = 0 + \frac{b}{4}(1+1)$

$\Rightarrow a = -1/2, b = -2 \Rightarrow :N^\dagger N: = -\frac{J_R J_L}{2} - 2 \vec{J}_R \vec{J}_L$ (in the sense of normal order).

Let's check $N^\dagger N = \frac{-1}{4} \psi_{R\alpha}^+ \psi_{R\delta} \psi_{L\beta}^+ \psi_{L\gamma} (\vec{\sigma}_{\alpha\beta})_{\alpha\beta} (\vec{\sigma}_{\gamma\delta})_{\gamma\delta}$

$$= a \psi_{R\alpha}^+ \psi_{R\alpha} \psi_{L\beta}^+ \psi_{L\beta} + \frac{b}{4} \psi_{R\alpha}^+ \sigma_{\alpha\beta}^a \psi_{R\beta} \psi_{L\gamma}^+ \sigma_{\gamma\delta}^a \psi_{L\delta}$$

Choose $\alpha = \beta = \gamma = \delta = \uparrow$

LHS = $\frac{-1}{4} \psi_{R\uparrow}^+ \psi_{R\uparrow} \psi_{L\uparrow}^+ \psi_{L\uparrow} \Rightarrow \frac{-1}{4} = a + \frac{b}{4}$

Choose $\alpha = \delta = \uparrow, \beta = \gamma = \downarrow$

LHS: $\frac{-1}{4} \psi_{R\uparrow}^+ \psi_{R\downarrow} \psi_{L\downarrow}^+ \psi_{L\uparrow} (\sigma_{\uparrow\downarrow}^x \sigma_{\downarrow\uparrow}^x + \sigma_{\uparrow\downarrow}^y \sigma_{\downarrow\uparrow}^y) = -\frac{1}{2} \psi_{R\uparrow}^+ \psi_{R\downarrow} \psi_{L\downarrow}^+ \psi_{L\uparrow}$

RHS $\Rightarrow a \psi_{R\uparrow}^+ \psi_{R\uparrow} \psi_{L\downarrow}^+ \psi_{L\downarrow} + \frac{b}{4} \psi_{R\uparrow}^+ \sigma_{\uparrow\downarrow}^3 \psi_{R\downarrow} \psi_{L\downarrow}^+ \sigma_{\downarrow\uparrow}^3 \psi_{L\uparrow}$

$\Rightarrow -1/2 = a - \frac{b}{4} \Rightarrow a = -3/8, b = 1/2$

for spin $1/2$ system, we define $N^\dagger = \psi_{R\sigma}^\dagger \psi_{L\sigma}$, $\vec{N}^\dagger = \psi_{R\alpha}^\dagger \left(\frac{\sigma}{2}\right)_{\alpha\beta} \psi_{L\beta}$

$$N^\dagger N = \psi_{R\sigma}^\dagger \psi_{L\sigma} \psi_{L\sigma'}^\dagger \psi_{R\sigma'} = -\psi_{R\sigma}^\dagger \psi_{R\sigma'}^\dagger \psi_{L\sigma'} \psi_{L\sigma} = -\{[\psi_{R\uparrow}^\dagger \psi_{R\uparrow} + \psi_{R\downarrow}^\dagger \psi_{R\downarrow}][\psi_{L\uparrow}^\dagger \psi_{L\uparrow} + \psi_{L\downarrow}^\dagger \psi_{L\downarrow}]/2$$

$$+ [\psi_{R\uparrow}^\dagger \psi_{R\downarrow} - \psi_{R\downarrow}^\dagger \psi_{R\uparrow}][\psi_{L\uparrow}^\dagger \psi_{L\downarrow} - \psi_{L\downarrow}^\dagger \psi_{L\uparrow}] + \psi_{R\uparrow}^\dagger \psi_{R\downarrow} \psi_{L\downarrow}^\dagger \psi_{L\uparrow} + h.c.\} = -\frac{J_R J_L}{2} - 2\vec{J}_R \cdot \vec{J}_L$$

$$\vec{N}^\dagger \vec{N} = : \psi_{R\alpha}^\dagger \psi_{L\beta}^\dagger : : \psi_{L\gamma} \psi_{R\delta} : \left(\frac{\sigma}{2}\right)_{\alpha\beta} \left(\frac{\sigma}{2}\right)_{\gamma\delta} = -\frac{1}{4} \psi_{R\alpha}^\dagger \psi_{R\sigma}^\dagger \psi_{L\gamma} \psi_{L\beta} (2\delta_{\alpha\sigma} \delta_{\beta\gamma} - \delta_{\alpha\beta} \delta_{\sigma\gamma})$$

$$= -\frac{1}{2} J_R J_L + \frac{1}{4} \psi_{R\alpha}^\dagger \psi_{R\sigma}^\dagger \psi_{L\gamma} \psi_{L\alpha} = -\frac{1}{2} J_R J_L + \frac{1}{4} \left(\frac{J_R J_L}{2} + 2\vec{J}_R \cdot \vec{J}_L\right)$$

$$= -\frac{3}{8} J_R J_L + \frac{1}{2} \vec{J}_R \cdot \vec{J}_L$$

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how about for spin $3/2$ system $N^\dagger = \psi_{R\alpha}^\dagger \psi_{L\alpha}$, $\vec{N}^\dagger = \psi_{R\alpha}^\dagger \left(\frac{\rho}{2}\right)_{\alpha\beta} \psi_{L\beta}$

$$N^\dagger N = \psi_{R\alpha}^\dagger \psi_{L\alpha} \psi_{L\beta}^\dagger \psi_{R\beta} = -\psi_{R\alpha}^\dagger \psi_{R\beta}^\dagger \psi_{L\beta} \psi_{L\alpha}$$

since its ~~SU(4)~~ SU(4) singlet, it must be

$$N^\dagger N = a \psi_{R\alpha}^\dagger \psi_{R\alpha} \psi_{L\beta}^\dagger \psi_{L\beta} + b \left(\psi_{R\alpha}^\dagger \frac{\rho^a}{2} \psi_{R\beta} \psi_{L\gamma}^\dagger \frac{\rho^a}{2} \psi_{L\delta} + \psi_{R\alpha}^\dagger \frac{\rho^{ab}}{2} \psi_{R\beta} \psi_{L\gamma}^\dagger \frac{\rho^{ab}}{2} \psi_{L\delta} \right)$$

choose LHS $\alpha=\beta=3/2 \Rightarrow -\psi_{R3/2}^\dagger \psi_{R3/2} \psi_{L3/2}^\dagger \psi_{L3/2}$

$$\text{RHS} = a \psi_{R3/2}^\dagger \psi_{R3/2} \psi_{L3/2}^\dagger \psi_{L3/2} + \frac{b}{4} \left[\psi_{R3/2}^\dagger \rho^4 \psi_{R3/2} \psi_{L3/2}^\dagger \rho^4 \psi_{L3/2} + \psi_{R3/2}^\dagger \rho^{15} \psi_{R3/2} \psi_{L3/2}^\dagger \rho^{15} \psi_{L3/2} \right. \\ \left. + \psi_{R3/2}^\dagger \rho^{23} \psi_{R3/2} \psi_{L3/2}^\dagger \rho^{23} \psi_{L3/2} \right]$$

$$\Rightarrow -1 = a + \frac{b}{4} (1+1+1) \quad \text{i.e.} \quad -1 = a + \frac{3b}{4}$$