

## HW 2

9.22: Set  $S_0$  the inertial frame, the Eq of motion reads

$$m \left( \frac{d^2 \vec{r}}{dt^2} \right)_{S_0} = - \frac{qQ}{r^2} \hat{r} + q \left( \frac{d\vec{r}}{dt} \right)_{S_0} \times \vec{B}$$

now let us change to a frame  $S$  rotating with angular velocity

$\vec{\Omega}$  relative to  $S_0$ . Then LHS

$$m \left( \frac{d^2 \vec{r}}{dt^2} \right)_{S_0} = m \left( \frac{d^2 \vec{r}}{dt^2} \right)_S - 2m \left( \frac{d\vec{r}}{dt} \right)_S \times \vec{\Omega} + m (\vec{\Omega} \times \vec{r}) \times \vec{\Omega}$$

$$\text{RHS} \Rightarrow - \frac{qQ}{r^2} \hat{r} + q \left[ \left( \frac{d\vec{r}}{dt} \right)_S + \vec{\Omega} \times \vec{r} \right] \times \vec{B}$$

Let us choose  $\vec{\Omega} = - \frac{q\vec{B}}{2m}$ , then  $\left( \frac{d\vec{r}}{dt} \right)_S$  in the Coriolis force (LHS)  
and Lorentz force (RHS)

cancels

$$\Rightarrow m \left( \frac{d^2 \vec{r}}{dt^2} \right)_S - \frac{q^2}{4m} (\vec{B} \times \vec{r}) \times \vec{B} = - \frac{qQ}{r^2} \hat{r} - \frac{q^2}{2m} (\vec{B} \times \vec{r}) \times \vec{B}$$

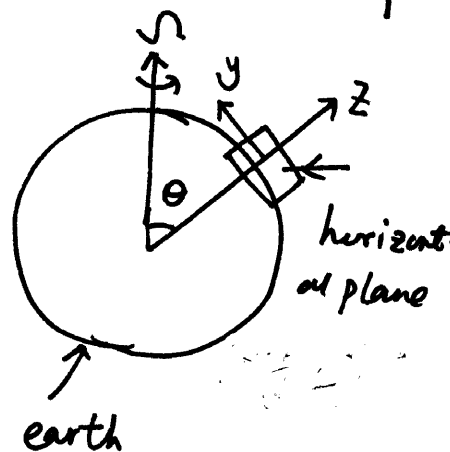
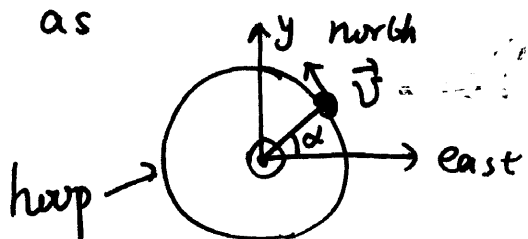
$$\Rightarrow m \left( \frac{d^2 \vec{r}}{dt^2} \right)_S = - \frac{qQ}{r^2} \hat{r} - \frac{q^2}{4m} (\vec{B} \times \vec{r}) \times \vec{B}$$

if  $B$  is weak, we can drop the second term, then the motion is in an inverse square force. Thus in " $S$ ", the motion is ellipse/hyperbola and in " $S_0$ ", the ellipse precesses.

9.30

The configuration of the hoop is plotted

as



The hoop is put in the  $xy$  (east-north) horizontal plane. It is spinning around the  $z$ -axis. Pick a small segment from  $\alpha \rightarrow \alpha + d\alpha$

$$\Rightarrow dm = \frac{m}{2\pi} d\alpha$$

$$d\vec{F}_{\text{cur}} = 2dm \vec{v} \times \vec{\omega}, \quad \vec{v} = \omega r (-\sin\alpha, \cos\alpha, 0)$$

$$\vec{\omega} = \omega (0, \sin\theta, \cos\theta)$$

$$\Rightarrow \cancel{d\vec{F}_{\text{cur}}} =$$

$$d\vec{P} = \vec{r} \times d\vec{F}_{\text{cur}} = 2dm \vec{r} \times (\vec{v} \times \vec{\omega})$$

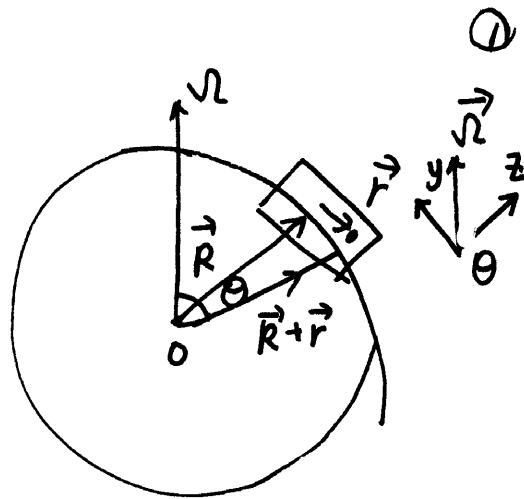
$$= 2dm [\vec{v} (\vec{r} \cdot \vec{\omega}) - \vec{\omega} (\vec{r} \cdot \vec{v})] = \frac{2dm}{\sin\theta} \omega r^2 \omega (-\sin^2\alpha, \sin\alpha \cos\alpha, 0)$$

$$\vec{P} = \int d\vec{P}$$

$$\Rightarrow \vec{P} = \hat{x} (-2 \sin\theta \omega r^2 \omega m \int_0^{2\pi} \frac{\sin^2\alpha}{2\pi} d\alpha) = -m \omega r^2 \omega \sin\theta \hat{x}$$

$\vec{P}$  along  $\hat{y}, \hat{z}$  are zero.

9.34: The puck's position at  $\vec{R} + \vec{r}$  respect to the center of the earth.  $\vec{R}$  is the center of the platform, and  $\vec{r}$  is respect to the center of the platform.  $\vec{R} \perp \vec{r}$ .



$$m \ddot{\vec{r}} = m \vec{g}_0(r) + 2m \dot{\vec{r}} \times \vec{\Omega} + m [(\vec{\Omega} \times (\vec{r} + \vec{R})) \times \vec{\Omega}] + \vec{F}_{\text{other}}$$

$$\vec{g}_0(r) = -GM \frac{\vec{R} + \vec{r}}{|\vec{R} + \vec{r}|^3} = -GM \frac{\vec{R} + \vec{r}}{(R^2 + r^2)^{3/2}} \approx -GM \frac{\vec{R} + \vec{r}}{R^3} \left(1 - \frac{3r^2}{2R^2}\right)$$

$$\approx -GM \frac{\vec{R}}{R^3} - \frac{GM \vec{r}}{R^3} = \vec{g}_0(0) + g_0 \frac{\vec{r}}{R}$$

The centrifugal force =  $m(\vec{\Omega} \times \vec{R}) \times \vec{\Omega} + m(\vec{\Omega} \times \vec{r}) \times \vec{\Omega}$

The first term combines with  $\vec{g}_0(0)$  as the actual free-fall acceleration  $\vec{g}(0)$ . The second term  $m(\vec{\Omega} \times \vec{r}) \times \vec{\Omega}$  can be dropped which will be justified later.  $\parallel \vec{F}'$

$\Rightarrow$  The equation of motion

$$\ddot{\vec{r}} = \vec{g}(0) - g \frac{\vec{r}}{R} + 2 \dot{\vec{r}} \times \vec{\Omega} + \frac{\vec{F}_{\text{other}}}{m}$$

Considering the in-plane motion, and remember

$$\vec{r} = (x, y, 0). \quad \vec{\Omega} = \Omega [0, \sin\theta, \cos\theta]$$

$$\Rightarrow \begin{cases} \ddot{x} = -\frac{g x}{R} + 2\dot{y}\Omega\omega_s\theta \\ \ddot{y} = -\frac{g y}{R} - 2\dot{x}\Omega\omega_s\theta \end{cases} \quad \text{define } \omega_0 = \sqrt{\frac{g}{R}} = 1.24 \times 10^{-3} \text{ s}^{-1} \quad \text{where } R = 6400 \text{ km}$$

This is the same equation of Foucault Pendulum.

$$\Omega_0 = \frac{2\pi}{24 \text{ hours}} \approx 7 \times 10^{-5} \text{ s}^{-1}, \quad \Rightarrow \omega_0 \gg \Omega$$

$\Rightarrow$  the puck oscillates with  $\omega_0$ , and precesses with  $\Omega_z = \Omega \cos\theta$

The ~~center~~ second term of the centrifugal force we dropped

$$F' = m(\vec{\Omega} \times \vec{r}) \times \vec{v} \sim m\Omega^2 A \quad \text{where } A \text{ is the amplitude}$$

$$F_{cr} \sim m\Omega v \sim m\Omega\omega_0 A$$

$$\Rightarrow \frac{F'}{F_{cr}} \sim \frac{\Omega}{\omega_0} \ll 1$$

and the gravity restoring force  $\frac{mg r}{R} \sim m A \omega_0^2 \gg F_{cr}, F'$

So  $\vec{F}'$  can indeed be dropped.